
Contents

Chapter 1	Introduction and Discrete Problems	2
1.1	Introduction, 4	
1.1.1	Typical applications	
1.1.1.1	Solid mechanics—structures	
1.1.1.2	Fluid mechanics	
1.1.1.3	Heat transfer	
1.1.1.4	Groundwater seepage	
1.2	Basic ingredients—discrete problems, 7	
1.3	Examples of discrete problems, 13	
1.3.1	Equilibrium of a spring-mass system—vectorial approach	
1.3.2	Equilibrium of a spring-mass system—variational approach	
1.3.3	Steady state heat transfer	
1.3.4	Piping networks	
1.3.5	Plane truss structures	
1.4	Closure, 37	
	References, 37	
	Computer projects, 38	
	Exercises, 41	
Chapter 2	One-Dimensional Boundary Value Problems	50
2.1	Introduction, 52	
2.2	The general problem, 52	
2.3	Approximate methods—weighted residuals, 56	
2.4	Variational methods, 62	
2.4.1	The weak formulation	
2.4.2	Calculus of variations	
2.4.2.1	Approximate method of Ritz	

2.5	Finite element formulations, 80	
2.5.1	Variational finite element model	
2.5.2	The Galerkin finite element model	
2.6	Eigenvalue problems, 97	
2.7	Evaluation of elementary matrices, 99	
2.8	Example applications, 116	
2.8.1	Solid mechanics—axial deformation	
2.8.2	Fluid mechanics—thin-film lubrication	
2.8.3	One-dimensional heat conduction with convection	
2.8.4	Torsional vibrations	
2.9	Higher order interpolations, 148	
2.10	One-dimensional quadratic interpolation examples, 157	
2.10.1	Solid mechanics—axial deformation	
2.10.2	Fluid mechanics—thin-film lubrication	
2.10.3	One-dimensional heat conduction with convection	
2.10.4	Torsional vibrations	
2.11	Transverse deflections of beams, 170	
2.12	Errors and convergence, 181	
2.13	Closure, 189	
	References, 191	
	Computer projects, 193	
	Exercises, 194	

Chapter 3	Two-Dimensional Boundary Value Problems	216
3.1	Introduction, 218	
3.1.1	Problem statement	
3.2	The weak formulation and variational principle, 220	
3.3	Finite element formulations, 223	
3.3.1	Ritz finite element model	
3.3.2	Galerkin finite element model	
3.4	Evaluation of matrices—linearly interpolated triangular elements, 239	
3.5	Example applications, 248	
3.5.1	Torsion of a rectangular section	
3.5.2	Conduction heat transfer with boundary convection	

3.6	Rectangular elements, 263
3.6.1	Evaluation of matrices
3.6.2	Torsion of a rectangular section
3.6.3	Conduction heat transfer with boundary convection
3.7	Eigenvalue problems, 278
3.7.1	Introduction
3.7.2	Finite element models for the Helmholtz equation
3.7.3	Examples for the Helmholtz equation
3.8	Isoparametric elements and numerical integration, 287
3.8.1	Four-node quadrilateral (Q4) elements
3.8.1.1	Transformations and shape functions
3.8.1.2	Evaluation of Q4 elemental matrices
3.8.1.3	Application—stress concentration for the torsion of an angle section
3.8.1.4	Application—steady state heat transfer
3.8.2	Eight-node quadrilateral (Q8) elements
3.8.2.1	Transformations and shape functions
3.8.2.2	Evaluation of Q8 elemental matrices
3.8.2.3	Application—stress concentration for the torsion of an angle section
3.8.2.4	Application—steady state heat transfer
3.8.3	Six-node triangular (T6) elements
3.8.3.1	Transformations and shape functions
3.8.3.2	Evaluation of T6 elemental matrices
3.8.3.3	Application—stress concentration for the torsion of an angle section
3.8.3.4	Application—steady state heat transfer
3.9	Axisymmetric problems, 359
3.10	Closure, 370
	References, 374
	Computer projects, 375
	Exercises, 377

Chapter 4 Time Dependent Problems 402

4.1	Introduction, 404
4.2	One-dimensional diffusion or parabolic equations, 404
4.2.1	The Galerkin finite element model
4.2.2	Example of one-dimensional diffusion
4.2.3	Analytical integration techniques

- 4.2.4 Time domain integration techniques—first-order systems
 - 4.2.4.1 The Euler method
 - 4.2.4.2 Improved Euler or Crank-Nicolson method
 - 4.2.4.3 Analysis of algorithms

- 4.3 One-dimensional wave or hyperbolic equations, 431
 - 4.3.1 The Galerkin finite element model
 - 4.3.2 One-dimensional wave example
 - 4.3.3 Analytical integration techniques
 - 4.3.4 Time domain integration techniques—second-order systems
 - 4.3.4.1 Central difference method
 - 4.3.4.2 Newmark's method
 - 4.3.4.3 Analysis of algorithms

- 4.4 Two-dimensional diffusion, 462
- 4.5 Two-dimensional wave equations, 466
- 4.6 Closure, 470

References, 471

Computer projects, 471

Exercises, 474

Chapter 5 Elasticity

482

- 5.1 Introduction, 484
 - 5.1.1 Kinetics
 - 5.1.2 Kinematics
 - 5.1.3 Constitution
 - 5.1.4 Combination—boundary value problems
 - 5.1.4.1 Plane stress
 - 5.1.4.2 Plane strain
- 5.2 Weak formulation and variational principles, 491
- 5.3 Ritz finite element model, 495
- 5.4 Evaluation of elemental matrices, 503
- 5.5 Applications, 509
 - 5.5.1 Uniform tension of a thin rectangular plate
 - 5.5.2 Thin rectangular plate—moment loading
 - 5.5.3 Thin rectangular plate—moment loading, meshes two and three
 - 5.5.4 Stress concentration—plate with circular hole

5.6	Rectangular elements, 535
5.6.1	Thin rectangular plate—moment loading
5.6.2	Thin rectangular plate—moment loading, meshes two and three
5.7	Axisymmetric problems, 552
5.7.1	Ritz finite element model—triangular elements
5.7.2	Evaluation of elemental matrices
5.7.2.1	Thick-walled pressure vessel
5.7.2.2	Notched shaft under tension
5.8	Isoparametric formulations, 574
5.8.1	Applications
5.8.1.1	Thin rectangular plate—moment loading
5.8.1.2	Stress concentration—plate with circular hole
5.9	Closure, 593
	References, 595
	Computer projects, 596
	Exercises, 598

Appendix A	Linear Algebraic Equations	606
Appendix B	Eigenvalue Problems	614
Appendix C	Solvability of Finite Element Equations	639
Index		645