

Contents

Part I. The Direct Boundary Element Method	
1. Introduction	3
1.1 Numerical Solution of Engineering Problems	3
1.2 Historic Development of Boundary Element Method	6
1.3 The Method of Weighted Residuals	7
1.3.1 Collocation Method	8
1.3.2 Method of Moments	9
1.3.3 Galerkin's Method	9
1.3.4 Collocation by Subregions	9
1.3.5 Least Squares	10
1.3.6 Summary	11
1.4 Boundary Elements vs. Finite Elements	11
1.4.1 General Features	12
1.4.2 Comparison of FE and BE Formulations	13
1.5 Boundary Integral Method for 1-D Differential Equation	16
1.6 General Boundary Element Approach	20
2. Mathematical Preliminaries	23
2.1 Notation	23
2.1.1 Vector Notation and Matrix Representation of Vectors	23
2.1.2 Index Notation	25
2.2 Theory of Distributions	26
2.2.1 Definition and Rules	27
2.2.2 Dirac Distribution and Heaviside Function	27
2.3 Integral Theorems	29
2.4 Time-Harmonic Motion	30
2.5 Introduction to the Calculus of Variations	31
3. Continuum Physics	35
3.1 Introduction	35
3.1.1 Continuous Media	35
3.1.2 Variables and Equations of State	36
3.1.3 Crystal Structure of a Continuous Medium	37
3.2 Elastodynamics	38

3.2.1	Kinematics	39
3.2.2	Kinetics	43
3.2.3	Conservation of Mass - The Continuity Equation	44
3.2.4	Conservation of Linear Momentum	46
3.2.5	Conservation of Angular Momentum	47
3.2.6	Conservation of Energy	48
3.2.7	Constitutive Equation	50
3.2.8	Field Equations and Boundary Conditions	53
3.2.9	Elastodynamic Wave Equations	55
3.2.10	Waves in Anisotropic Materials	56
3.3	Heat Conduction	60
3.3.1	First Law of Thermodynamics	60
3.3.2	Second Law of Thermodynamics	61
3.3.3	Field Equations of Heat Conduction	63
3.3.4	Boundary and Initial Conditions	64
3.4	Electrodynamics.....	65
3.4.1	Maxwell's Equations in Vacuum.....	65
3.4.2	Electromagnetic Wave Equations	67
3.4.3	Electrostatic Field in Macroscopic Media	68
3.4.4	Field Equation for Dielectrics	68
3.4.5	Electric Jump Conditions at Interfaces	70
3.4.6	Electric Boundary Conditions for an Ideal Conductor ..	70
3.5	Thermoelasticity	71
3.5.1	First Law of Thermodynamics	71
3.5.2	Second Law of Thermodynamics	72
3.5.3	Constitutive Equations.....	73
3.5.4	Field Equations of Thermoelasticity	76
3.5.5	Simplified Thermoelastic Theories	77
3.6	Acoustics.....	79
3.6.1	The Acoustic Wave Equation	80
3.6.2	Constitutive Equations.....	81
3.6.3	The Velocity Potential	86
3.6.4	Boundary Conditions in Acoustics	86
3.6.5	Radiation Condition in Infinite Domains	87
3.7	Piezoelectricity	89
3.7.1	Polarisation in Piezoelectrics	90
3.7.2	Energy Balance and Thermodynamic Potentials	91
3.7.3	Constitutive Equations.....	92
3.7.4	Field Equations of Piezoelectricity	93
4.	Boundary Element Method for Potential Problems	95
4.1	Introduction	95
4.2	BE Formulation of Laplace's Equation	96
4.2.1	Inverse Formulation of Differential Equation	96
4.2.2	Green's Representation Formula.....	98

4.2.3	Fundamental Solutions	99
4.2.4	Boundary Integral Equation of the 2-D Problem	99
4.2.5	Discretisation of the Boundary	104
4.2.6	The Collocation Method	107
4.2.7	Modelling of Discontinuous Fluxes	110
4.3	Example: Steady-State Heat Conduction	114
4.3.1	Calculation of System Matrices	114
4.3.2	Assembly and Solution of Equations	120
4.3.3	The Analytical Solution	121
4.4	Calculation of Solution in the Domain	122
4.4.1	Potential in the Domain	122
4.4.2	Flux in the Domain	123
4.5	Poisson's Equation – Treatment of Source Terms	123
4.5.1	Calculation of Domain Integral by Cell Integration	124
4.5.2	Calculation of Domain Integral by Transformation to a Boundary Integral	127
4.5.3	Calculation of the Unknown Boundary Variables	130
4.6	Indirect Calculation of Diagonal Entries of $\mathbf{H}$	131
4.7	Concentrated Sources	131
4.8	Subdomains	132
4.9	Orthotropic Heat Conduction	134
4.10	Example: Coupling of Orthotropic and Isotropic Subdomains	136
4.10.1	Calculation of Matrix Elements H_{78} and G_{78}	138
4.10.2	Analytical Solution	140
5.	Boundary Element Method for Elastic Continua	141
5.1	Integral Formulation of Equation of Motion	141
5.1.1	Method of Weighted Residuals	141
5.1.2	Inverse Statement	142
5.1.3	Reciprocal Work Principle	145
5.1.4	Somigliana's Identity	146
5.2	Derivation of Boundary Integral Equation	149
5.2.1	Boundary Extension Around Load Point	149
5.2.2	Integration over Boundary Extension Γ_ε	151
5.2.3	Boundary Integral Equation	152
5.3	Numerical Implementation	152
5.3.1	Discretisation with Boundary Elements	153
5.3.2	Approximation of Boundary Variables	156
5.3.3	Matrix Assembly	157
5.4	Implementation of Anisotropic Fundamental Solutions	160
5.4.1	Fundamental Solutions in Elastostatics	160
5.4.2	Interpolation Scheme for Anisotropic Fundamental So- lution	161
5.4.3	Evaluation of Anisotropic Fundamental Solution	165
5.5	Static Piezoelectricity	168

5.5.1	Contracted Notation	168
5.5.2	Boundary Element Formulation	170
5.5.3	Numerical Example	171
6.	Numerical Integration	175
6.1	Regular Integration in 1-D	176
6.1.1	Simpson's Rule	176
6.1.2	Gaussian Quadrature	179
6.2	Regular Integration in 2-D and 3-D	183
6.2.1	Multidimensional Gaussian Quadrature	183
6.2.2	Numerical Integration over Boundary Elements	184
6.3	Weakly Singular Integration	187
6.3.1	Weak Singularity in 2-D BEM	187
6.3.2	Weak Singularity in 3-D BEM	188
6.4	Strongly Singular Integration	193
6.4.1	Strong Singularity in 2-D BEM	193
6.4.2	Strong Singularity in 3-D BEM	199

Part II. The Dual Reciprocity Method

7.	DRM for Potential Problems and Elastodynamics	207
7.1	Introduction	207
7.2	Dual Reciprocity Formulation for Poisson's Equation	209
7.2.1	Dual Representation Formula	209
7.2.2	Boundary Integral Equation and Discretisation	211
7.2.3	Coefficients α and System of Equations	213
7.2.4	Calculation of Interior Values	214
7.3	The Wave Equation	214
7.4	The Helmholtz Equation	217
7.5	Transient Heat Conduction	218
7.6	Anisotropic Elastodynamics	219
7.6.1	Representation Formula	220
7.6.2	Dual Reciprocity Formulation	220
7.6.3	Boundary Integral Equation and System of Equations	222
7.7	Particular Solutions	223
7.7.1	Types of Interpolation Functions	223
7.7.2	Interpolation Functions in Anisotropic Analysis	225
8.	Solution of the Equations of Motion	227
8.1	System of Equations	227
8.2	The Elliptic Problem: Static and Time-Harmonic Analysis ...	228
8.2.1	Solution of the Equations	228
8.2.2	Numerical Example	229
8.3	The Eigenproblem: Free Vibration Analysis	231

8.3.1	Solution of the Eigenvalue Problem	231
8.3.2	Numerical Example	232
8.4	The Hyperbolic Problem: Transient Analysis	237
8.4.1	Direct Analysis	238
8.4.2	Modal Superposition	240
8.4.3	Instabilities in Time Integration	243
8.4.4	Numerical Example	250
8.5	The Parabolic Problem: Transient Heat Conduction	253
9.	Dynamic Piezoelectricity	255
9.1	Dual Reciprocity Formulation	255
9.2	Coefficients α and System of Equations	257
9.3	Solution of Piezoelectric Equations	258
9.4	Numerical Example	260
10.	Coupled Thermoelasticity	263
10.1	Representation Formulae	263
10.1.1	Elastic Representation Formula	264
10.1.2	Thermal Representation Formula	265
10.1.3	Thermoelastic Representation Formula	265
10.2	Dual Reciprocity Formulation	267
10.3	The Coefficients α	269
10.4	System of Equations	271
10.5	Solution of Thermoelastic Equations	272
10.5.1	Stationary Thermoelasticity	273
10.5.2	Uncoupled Quasi-Static Thermoelasticity	273
10.5.3	Theory of Thermal Stresses	273
10.5.4	Coupled Quasi-Static Thermoelasticity	274
10.5.5	Fully Coupled Thermoelasticity	275
10.6	Numerical Examples	275
10.6.1	Stationary Thermoelasticity	275
10.6.2	Quasi-Static Thermoelasticity	278

Part III. Hybrid Boundary Element Methods

11.	Variational Principles of Continuum Mechanics	283
11.1	Virtual Quantities in Continuum Mechanics	283
11.1.1	Virtual Work	284
11.1.2	Strain Energy	285
11.1.3	Complementary Strain Energy	286
11.2	Single-Field Principles	287
11.2.1	Elastostatics	287
11.2.2	Elastodynamics	289
11.3	Generalised Principles	292

11.3.1	Elastostatics	292
11.3.2	Elastodynamics	293
12.	The Hybrid Displacement Method	297
12.1	Introduction with Laplace's Equation	297
12.2	Discretisation of the First Variation	299
12.2.1	Boundary Approximation	300
12.2.2	Domain Approximation	300
12.2.3	Domain Modification	302
12.3	Matrix Formulation for Potential Problems	303
12.3.1	Example for Laplace's Equation	304
12.4	The HDBEM for Elastodynamics	310
12.4.1	Transformation to the Frequency Domain	313
12.4.2	Discretisation of the First Variation	315
12.4.3	Matrix Formulation in Elastodynamics	317
12.4.4	Computation of Field Points	319
12.5	Numerical Implementation	319
12.5.1	The $\mathbf{L}$ Matrix	319
12.5.2	The Vector of Equivalent Nodal Loads	320
12.5.3	The $\mathbf{F}$ Matrix	321
12.5.4	Efficient Calculation of the $\mathbf{F}$ Matrix	332
12.6	The Concept of Rigid Body Motion in Elastostatics	336
12.7	Harmonic Bending Waves of Beams	338
12.7.1	Hybrid Integral Formulation for the Beam	341
12.7.2	Example: Viscoelastic Beam Element	348
13.	The Hybrid Stress Method for Acoustics	351
13.1	Hellinger-Reissner Principle for Acoustics	351
13.2	Matrix Formulation	354
13.2.1	Efficient Field Point Computation	356
13.3	Numerical Implementation for Acoustics	360
13.4	Orthogonality Properties of the HSBEM	362
13.4.1	Coordinate Sets and Transformation Relations	362
13.4.2	Finite Domains	364
13.4.3	Determination of the Fundamental Solution Matrix $\tilde{\phi}_0^*$	367
13.4.4	Infinite Domains	373
13.5	Applications in Acoustics	375
13.5.1	Interior Problems	376
13.5.2	An Exterior Problem	378
13.6	Fluid-Structure Interaction in the Frequency Domain	381
13.6.1	Model of Acoustic Fluid-Structure Interaction	381
13.6.2	Coupled Multi-Field Problem	385
13.6.3	Sound Radiation by Bending Waves	390

14. The Hybrid Boundary Element Method in Time Domain .	399
14.1 Time-domain Formulation for Elastodynamics	400
14.1.1 Non-Singular Formulation of the HDBEM	401
14.1.2 Positioning of the Load Points	404
14.1.3 Transformation of the Mass Matrix to the Boundary . .	405
14.1.4 Numerical Examples	406
14.2 Time-domain Formulation for Acoustics	413
14.2.1 Hybrid Boundary Element Formulation for the Fluid . .	414
14.2.2 Approximation of Domain and Boundary Variables . .	415
14.2.3 Boundary Integral Formulation	416
14.2.4 System of Discretised Equations	417
14.2.5 Numerical Examples	419
14.3 Fluid-Structure Interaction in the Time Domain	421

Part IV. Appendices

A. Properties of Elastic Materials	431
B. Fundamental Solutions	433
B.1 Potential Problems	433
B.1.1 Laplace's Equation	433
B.1.2 The Helmholtz Equation	437
B.1.3 Anisotropic Form of Laplace's equation	440
B.2 Elastomechanics	442
B.2.1 Isotropic Elastostatics	442
B.2.2 Anisotropic Elastostatics	445
B.2.3 Isotropic Time-Harmonic Elastodynamics	448
B.2.4 Anisotropic Elastodynamics	451
B.3 Piezoelectricity	451
B.3.1 Static Piezoelectricity	452
B.3.2 Dynamic Piezoelectricity	453
C. Particular Solutions	455
C.1 Poisson's Equation	455
C.2 Anisotropic Heat Conduction	457
C.3 Isotropic Elastostatics	457
C.4 Anisotropic Elastostatics	459
C.5 Piezoelectricity	459
D. The Bott-Duffin Inverse	461
References	463
Index	477