

Contents

Preface	xi
Series Preface	xiii
Notation	xv
About the Code	xxi

PART I BASIC CONCEPTS AND SOLUTION TECHNIQUES

1 Preliminaries	3
1.1 A Simple Example of Non-linear Behaviour	3
1.2 A Review of Concepts from Linear Algebra	5
1.3 Vectors and Tensors	12
1.4 Stress and Strain Tensors	17
1.5 Elasticity	23
1.6 The PyFEM Finite Element Library	25
References	29
2 Non-linear Finite Element Analysis	31
2.1 Equilibrium and Virtual Work	31
2.2 Spatial Discretisation by Finite Elements	33
2.3 PyFEM: Shape Function Utilities	38
2.4 Incremental-iterative Analysis	41
2.5 Load <i>versus</i> Displacement Control	50
2.6 PyFEM: A Linear Finite Element Code with Displacement Control	53
References	62
3 Geometrically Non-linear Analysis	63
3.1 Truss Elements	64
3.1.1 <i>Total Lagrange Formulation</i>	67
3.1.2 <i>Updated Lagrange Formulation</i>	70
3.1.3 <i>Corotational Formulation</i>	72
3.2 PyFEM: The Shallow Truss Problem	76
3.3 Stress and Deformation Measures in Continua	85
3.4 Geometrically Non-linear Formulation of Continuum Elements	91
3.4.1 <i>Total and Updated Lagrange Formulations</i>	91
3.4.2 <i>Corotational Formulation</i>	96

3.5	Linear Buckling Analysis	100
3.6	PyFEM: A Geometrically Non-linear Continuum Element	103
	References	110
4	Solution Techniques in Quasi-static Analysis	113
4.1	Line Searches	113
4.2	Path-following or Arc-length Methods	116
4.3	PyFEM: Implementation of Riks' Arc-length Solver	124
4.4	Stability and Uniqueness in Discretised Systems	129
4.4.1	<i>Stability of a Discrete System</i>	129
4.4.2	<i>Uniqueness and Bifurcation in a Discrete System</i>	130
4.4.3	<i>Branch Switching</i>	134
4.5	Load Stepping and Convergence Criteria	134
4.6	Quasi-Newton Methods	138
	References	141
5	Solution Techniques for Non-linear Dynamics	143
5.1	The Semi-discrete Equations	143
5.2	Explicit Time Integration	144
5.3	PyFEM: Implementation of an Explicit Solver	149
5.4	Implicit Time Integration	152
5.4.1	<i>The Newmark Family</i>	153
5.4.2	<i>The HHT α-method</i>	154
5.4.3	<i>Alternative Implicit Methods for Time Integration</i>	155
5.5	Stability and Accuracy in the Presence of Non-linearities	156
5.6	Energy-conserving Algorithms	161
5.7	Time Step Size Control and Element Technology	164
	References	165
 PART II MATERIAL NON-LINEARITIES		
6	Damage Mechanics	169
6.1	The Concept of Damage	169
6.2	Isotropic Elasticity-based Damage	171
6.3	PyFEM: A Plane-strain Damage Model	175
6.4	Stability, Ellipticity and Mesh Sensitivity	179
6.4.1	<i>Stability and Ellipticity</i>	179
6.4.2	<i>Mesh Sensitivity</i>	182
6.5	Cohesive-zone Models	185
6.6	Element Technology: Embedded Discontinuities	190
6.7	Complex Damage Models	198
6.7.1	<i>Anisotropic Damage Models</i>	198
6.7.2	<i>Microplane Models</i>	199

6.8	Crack Models for Concrete and Other Quasi-brittle Materials	201
6.8.1	<i>Elasticity-based Smeared Crack Models</i>	201
6.8.2	<i>Reinforcement and Tension Stiffening</i>	206
6.9	Regularised Damage Models	210
6.9.1	<i>Non-local Damage Models</i>	210
6.9.2	<i>Gradient Damage Models</i>	211
	References	215
7	Plasticity	219
7.1	A Simple Slip Model	219
7.2	Flow Theory of Plasticity	223
7.2.1	<i>Yield Function</i>	223
7.2.2	<i>Flow Rule</i>	228
7.2.3	<i>Hardening Behaviour</i>	232
7.3	Integration of the Stress–strain Relation	239
7.4	Tangent Stiffness Operators	249
7.5	Multi-surface Plasticity	252
7.5.1	<i>Koiter's Generalisation</i>	252
7.5.2	<i>Rankine Plasticity for Concrete</i>	254
7.5.3	<i>Tresca and Mohr–Coulomb Plasticity</i>	260
7.6	Soil Plasticity: Cam-clay Model	267
7.7	Coupled Damage–Plasticity Models	270
7.8	Element Technology: Volumetric Locking	271
	References	277
8	Time-dependent Material Models	281
8.1	Linear Visco-elasticity	281
8.1.1	<i>One-dimensional Linear Visco-elasticity</i>	282
8.1.2	<i>Three-dimensional Visco-elasticity</i>	284
8.1.3	<i>Algorithmic Aspects</i>	285
8.2	Creep Models	287
8.3	Visco-plasticity	289
8.3.1	<i>One-dimensional Visco-plasticity</i>	289
8.3.2	<i>Integration of the Rate Equations</i>	291
8.3.3	<i>Perzyna Visco-plasticity</i>	292
8.3.4	<i>Duvaut–Lions Visco-plasticity</i>	294
8.3.5	<i>Consistency Model</i>	296
8.3.6	<i>Propagative or Dynamic Instabilities</i>	298
	References	303

PART III STRUCTURAL ELEMENTS

9	Beams and Arches	307
9.1	A Shallow Arch	307
9.1.1	<i>Kirchhoff Formulation</i>	307

9.1.2	<i>Including Shear Deformation: Timoshenko Beam</i>	314
9.2	PyFEM: A Kirchhoff Beam Element	317
9.3	Corotational Elements	321
9.3.1	<i>Kirchhoff Theory</i>	321
9.3.2	<i>Timoshenko Beam Theory</i>	326
9.4	A Two-dimensional Isoparametric Degenerate Continuum Beam Element	328
9.5	A Three-dimensional Isoparametric Degenerate Continuum Beam Element	333
	References	341
10	Plates and Shells	343
10.1	Shallow-shell Formulations	344
10.2	An Isoparametric Degenerate Continuum Shell Element	351
10.3	Solid-like Shell Elements	356
10.4	Shell Plasticity: Ilyushin's Criterion	357
	References	361
 PART IV LARGE STRAINS		
11	Hyperelasticity	365
11.1	More Continuum Mechanics	365
11.1.1	<i>Momentum Balance and Stress Tensors</i>	365
11.1.2	<i>Objective Stress Rates</i>	368
11.1.3	<i>Principal Stretches and Invariants</i>	372
11.2	Strain Energy Functions	374
11.2.1	<i>Incompressibility and Near-incompressibility</i>	376
11.2.2	<i>Strain Energy as a Function of Stretch Invariants</i>	378
11.2.3	<i>Strain Energy as a Function of Principal Stretches</i>	382
11.2.4	<i>Logarithmic Extension of Linear Elasticity: Hencky Model</i>	386
11.3	Element Technology	389
11.3.1	<i>u/p Formulation</i>	389
11.3.2	<i>Enhanced Assumed Strain Elements</i>	392
11.3.3	<i>F-bar Approach</i>	395
11.3.4	<i>Corotational Approach</i>	396
	References	398
12	Large-strain Elasto-plasticity	401
12.1	Eulerian Formulations	402
12.2	Multiplicative Elasto-plasticity	407
12.3	Multiplicative Elasto-plasticity <i>versus</i> Rate Formulations	411
12.4	Integration of the Rate Equations	414
12.5	Exponential Return-mapping Algorithms	418
	References	422

PART V ADVANCED DISCRETISATION CONCEPTS

13 Interfaces and Discontinuities	427
13.1 Interface Elements	428
13.2 Discontinuous Galerkin Methods	436
References	439
14 Meshless and Partition-of-unity Methods	441
14.1 Meshless Methods	442
14.1.1 <i>The Element-free Galerkin Method</i>	442
14.1.2 <i>Application to Fracture</i>	446
14.1.3 <i>Higher-order Damage Mechanics</i>	448
14.1.4 <i>Volumetric Locking</i>	450
14.2 Partition-of-unity Approaches	451
14.2.1 <i>Application to Fracture</i>	455
14.2.2 <i>Extension to Large Deformations</i>	460
14.2.3 <i>Dynamic Fracture</i>	465
14.2.4 <i>Weak Discontinuities</i>	468
References	470
15 Isogeometric Finite Element Analysis	473
15.1 Basis Functions in Computer Aided Geometric Design	473
15.1.1 <i>Univariate B-splines</i>	474
15.1.2 <i>Univariate NURBS</i>	478
15.1.3 <i>Multivariate B-splines and NURBS Patches</i>	478
15.1.4 <i>T-splines</i>	480
15.2 Isogeometric Finite Elements	483
15.2.1 <i>Bézier Element Representation</i>	483
15.2.2 <i>Bézier Extraction</i>	485
15.3 PyFEM: Shape Functions for Isogeometric Analysis	487
15.4 Isogeometric Analysis in Non-linear Solid Mechanics	490
15.4.1 <i>Design-through-analysis of Shell Structures</i>	491
15.4.2 <i>Higher-order Damage Models</i>	496
15.4.3 <i>Cohesive Zone Models</i>	500
References	506
Index	509