

CONTENTS

FOREWORD.....	8
INTRODUCTION.....	10
1 Scope.....	11
2 Normative references.....	11
3 Terms and definitions	11
4 Symbols and abbreviated terms	18
5 Preliminary considerations, main assumptions, and limitations.....	22
5.1 General considerations.....	22
5.2 Pre-requisite/main assumptions.....	23
5.3 Limitations	23
6 Establishment of system success/failed states	24
6.1 General considerations.....	24
6.2 Detailed considerations	24
6.2.1 System operation.....	24
6.2.2 Environmental conditions	25
6.2.3 Duty cycles	25
7 Elementary models.....	25
7.1 Developing the model.....	25
7.2 Series structures.....	25
7.3 Parallel structures.....	26
7.4 Mix of series and parallel structures.....	26
7.5 Other structures.....	27
7.5.1 m out of n structures.....	27
7.5.2 Structures with common blocks	28
7.5.3 Composite blocks.....	29
7.6 Large RBDs and use of transfer gates	29
8 Qualitative analysis: minimal tie sets and minimal cut sets.....	30
8.1 Electrical analogy.....	30
8.2 Series-parallel representation with minimal success path and cut sets.....	32
8.3 Qualitative analysis from minimal cut sets.....	33
9 Quantitative analysis: blocks with constant probability of failure/success	33
9.1 Series structures.....	33
9.2 Parallel structures.....	34
9.3 Mix of series and parallel structures.....	34
9.4 m/n architectures (identical items).....	35
10 Quantitative analysis: blocks with time dependent probabilities of failure/success	35
10.1 General.....	35
10.2 Non-repaired blocks	36
10.2.1 General	36
10.2.2 Simple non-repaired block.....	36
10.2.3 Non-repaired composite blocks.....	36
10.2.4 RBDs with non-repaired blocks.....	37
10.3 Repaired blocks	37
10.3.1 Availability calculations	37
10.3.2 Average availability calculations	40

10.3.3	Reliability calculations	42
10.3.4	Frequency calculations	43
11	Boolean techniques for quantitative analysis of large models	43
11.1	General	43
11.2	Method of RBD reduction	44
11.3	Use of total probability theorem	45
11.4	Use of Boolean truth tables	46
11.5	Use of Karnaugh maps	47
11.6	Use of the Shannon decomposition and binary decision diagrams	49
11.7	Use of Sylvester-Poincaré formula	50
11.8	Examples of RBD application	51
11.8.1	Models with repeated blocks	51
11.8.2	m out of n models (non-identical items)	54
12	Extension of reliability block diagram techniques	54
12.1	Non-coherent reliability block diagrams	54
12.2	Dynamic reliability block diagrams	57
12.2.1	General	57
12.2.2	Local interactions	58
12.2.3	Systemic dynamic interactions	59
12.2.4	Graphical representations of dynamic interactions	59
12.2.5	Probabilistic calculations	62
Annex A (informative)	Summary of formulae	63
Annex B (informative)	Boolean algebra methods	67
B.1	Introductory remarks	67
B.2	Notation	67
B.3	Tie sets (success paths) and cut sets (failure paths) analysis	68
B.3.1	Notion of cut and tie sets	68
B.3.2	Series-parallel representation using minimal tie and cut sets	69
B.3.3	Identification of minimal cuts and tie sets	70
B.4	Principles of calculations	71
B.4.1	Series structures	71
B.4.2	Parallel structures	71
B.4.3	Mix of series and parallel structures	73
B.4.4	m out of n architectures (identical items)	73
B.5	Use of Sylvester Poincaré formula for large RBDs and repeated blocks	74
B.5.1	General	74
B.5.2	Sylvester Poincaré formula with tie sets	74
B.5.3	Sylvester Poincaré formula with cut sets	76
B.6	Method for disjointing Boolean expressions	77
B.6.1	General and background	77
B.6.2	Disjointing principle	78
B.6.3	Disjointing procedure	79
B.6.4	Example of application of disjointing procedure	79
B.6.5	Comments	81
B.7	Binary decision diagrams	82
B.7.1	Establishing a BDD	82
B.7.2	Minimal success paths and cut sets with BDDs	84
B.7.3	Probabilistic calculations with BDDs	86

B.7.4	Key remarks about the use of BDDs	87
Annex C (informative)	Time dependent probabilities and RBD driven Markov processes	88
C.1	General	88
C.2	Principle for calculation of time dependent availabilities	88
C.3	Non-repaired blocks	89
C.3.1	General	89
C.3.2	Simple non-repaired blocks	89
C.3.3	Composite block: example on a non-repaired standby system	89
C.4	RBD driven Markov processes	91
C.5	Average and asymptotic (steady state) availability calculations	92
C.6	Frequency calculations	93
C.7	Reliability calculations	94
Annex D (informative)	Importance factors	96
D.1	General	96
D.2	Vesely-Fussell importance factor	96
D.3	Birnbaum importance factor or marginal importance factor	96
D.4	Lambert importance factor or critical importance factor	97
D.5	Diagnostic importance factor	97
D.6	Risk achievement worth	98
D.7	Risk reduction worth	98
D.8	Differential importance measure	98
D.9	Remarks about importance factors	99
Annex E (informative)	RBD driven Petri nets	100
E.1	General	100
E.2	Example of sub-PN to be used within RBD driven PN models	100
E.3	Evaluation of the DRBD state	102
E.4	Availability, reliability, frequency and MTTF calculations	104
Annex F (informative)	Numerical examples and curves	105
F.1	General	105
F.2	Typical series RBD structure	105
F.2.1	Non-repaired blocks	105
F.2.2	Repaired blocks	106
F.3	Typical parallel RBD structure	107
F.3.1	Non-repaired blocks	107
F.3.2	Repaired blocks	108
F.4	Complex RBD structures	109
F.4.1	Non series-parallel RBD structure	109
F.4.2	Convergence to asymptotic values versus MTTR	110
F.4.3	System with periodically tested components	111
F.5	Dynamic RBD example	113
F.5.1	Comparison between analytical and Monte Carlo simulation results	113
F.5.2	Dynamic RBD example	113
Bibliography		116
Figure 1	– Shannon decomposition of a simple Boolean expression and resulting BDD	18
Figure 2	– Series reliability block diagram	25
Figure 3	– Parallel reliability block diagram	26

Figure 4 – Parallel structure made of duplicated series sub-RBD	26
Figure 5 – Series structure made of parallel reliability block diagram.....	27
Figure 6 – General series-parallel reliability block diagram	27
Figure 7 – Another type of general series-parallel reliability block diagram	27
Figure 8 – 2 out of 3 redundancy	28
Figure 9 – 3 out of 4 redundancy	28
Figure 10 – Diagram not easily represented by series/parallel arrangement of blocks	28
Figure 11 – Example of RBD implementing dependent blocks	29
Figure 12 – Example of a composite block.....	29
Figure 13 – Use of transfer gates and sub-RBDs	30
Figure 14 – Analogy between a block and an electrical switch.....	30
Figure 15 – Analogy with an electrical circuit.....	31
Figure 16 – Example of minimal success path (tie set).....	31
Figure 17 – Example of minimal failure path (cut set).....	31
Figure 18 – Equivalent RBDs with minimal success paths	32
Figure 19 – Equivalent RBDs with minimal cut sets.....	33
Figure 20 – Link between a basic series structure and probability calculations	33
Figure 21 – Link between a parallel structure and probability calculations	34
Figure 22 – "Availability" Markov graph for a simple repaired block	38
Figure 23 – Standby redundancy	38
Figure 24 – Typical availability of a periodically tested block	39
Figure 25 – Example of RBD reaching a steady state.....	41
Figure 26 – Example of RBD with recurring phases	41
Figure 27 – RBD and equivalent Markov graph for reliability calculations	42
Figure 28 – Illustrating grouping of blocks before reduction.....	44
Figure 29 – Reduced reliability block diagrams	44
Figure 30 – Representation of Figure 10 when item A has failed	45
Figure 31 – Representation of Figure 10 when item A is working.....	45
Figure 32 – RBD representing three redundant items.....	46
Figure 33 – Shannon decomposition equivalent to Table 5.....	49
Figure 34 – Binary decision diagram equivalent to Table 5.....	49
Figure 35 – RBD using an arrow to help define system success	51
Figure 36 – Alternative representation of Figure 35 using repeated blocks and success paths.....	51
Figure 37 – Other alternative representation of Figure 35 using repeated blocks and minimal cut sets.....	52
Figure 38 – Shannon decomposition related to Figure 35.....	53
Figure 39 – 2-out-of-5 non-identical items	54
Figure 40 – Direct and inverted block	55
Figure 41 – Example of electrical circuit with a commutator A	55
Figure 42 – Electrical circuit: failure paths	55
Figure 43 – Example RBD with blocks with inverted states.....	56
Figure 44 – BDD equivalent to Figure 43	57
Figure 45 – Symbol for external elements.....	58

Figure 46 – Dynamic interaction between a CCF and RBDs' blocks.....	60
Figure 47 – Various ways to indicate dynamic interaction between blocks	60
Figure 48 – Dynamic interaction between a single repair team and RBDs' blocks	60
Figure 49 – Implementation of a PAND gate	61
Figure 50 – Equivalent finite-state automaton and example of chronogram for a PAND gate.....	61
Figure 51 – Implementation of a SEQ gate	61
Figure 52 – Equivalent finite-state automaton and example of chronogram for a SEQ gate	62
Figure B.1 – Examples of minimal tie sets (success paths)	68
Figure B.2 – Examples of non-minimal tie sets (non minimal success paths)	68
Figure B.3 – Examples of minimal cut sets	69
Figure B.4 – Examples of non-minimal cut sets.....	69
Figure B.5 – Example of RBD with tie and cut sets of various order	70
Figure B.6 – Reminder of the RBD in Figure 35	82
Figure B.7 – Shannon decomposition of the Boolean function represented by Figure B.6.....	82
Figure B.8 – Identification of the parts which do not matter	83
Figure B.9 – Simplification of the Shannon decomposition	83
Figure B.10 – Binary decision diagram related to the RBD in Figure B.6.....	84
Figure B.11 – Obtaining success paths (tie sets) from an RBD.....	84
Figure B.12 – Obtaining failure paths (cut sets) from an RBD.....	85
Figure B.13 – Finding cut and tie sets from BDDs.....	85
Figure B.14 – Probabilistic calculations from a BDD.....	86
Figure B.15 – Calculation of conditional probabilities using BDDs	87
Figure C.1 – Principle of time dependent availability calculations	88
Figure C.2 – Principle of RBD driven Markov processes	91
Figure C.3 – Typical availability of RBD with quickly repaired failures	91
Figure C.4 – Example of simple multi-phase Markov process	92
Figure C.5 – Typical availability of RBD with periodically tested failures	92
Figure E.1 – Example of a sub-PN modelling a DRBD block.....	100
Figure E.2 – Example of a sub-PN modelling a common cause failure.....	101
Figure E.3 – Example of DRBD based on RBD driven PN	101
Figure E.4 – Logical calculation of classical RBD structures.....	102
Figure E.5 – Example of logical calculation for an n/m gate	102
Figure E.6 – Example of sub-PN modelling a PAND gate with 2 inputs	103
Figure E.7 – Example of the inhibition of the failure of a block	104
Figure E.8 – Sub-PN for availability, reliability and frequency calculations.....	104
Figure F.1 – Availability/reliability of a typical non-repaired series structure	105
Figure F.2 – Failure rate and failure frequency related to Figure F.1	106
Figure F.3 – Equivalence of a non-repaired series structure to a single block.....	106
Figure F.4 – Availability/reliability of a typical repaired series structure	106
Figure F.5 – Failure rate and failure frequency related to Figure F.4	107
Figure F.6 – Availability/reliability of a typical non-repaired parallel structure	107
Figure F.7 – Failure rate and failure frequency related to Figure F.6	108
Figure F.8 – Availability/reliability of a typical repaired parallel structure	108

Figure F.9 – Vesely failure rate and failure frequency related to Figure F.8	109
Figure F.10 – Example 1 from 7.5.2	109
Figure F.11 – Failure rate and failure frequency related to Figure F.10.....	110
Figure F.12 – Impact of the MTTR on the convergence quickness	111
Figure F.13 – System with periodically tested blocks	112
Figure F.14 – Failure rate and failure frequency related to Figure F.13.....	112
Figure F.15 – Analytical versus Monte Carlo simulation results	113
Figure F.16 – Impact of CCF and limited number of repair teams	114
Figure F.17 – Markov graphs modelling the impact of the number of repair teams	115
Figure F.18 – Approximation for two redundant blocks	115
Table 1 – Acronyms used in IEC 61078	18
Table 2 – Symbols used in IEC 61078	19
Table 3 – Graphical representation of RBDs: Boolean structures	21
Table 4 – Graphical representation of RBDs: non-Boolean structures/DRBD	22
Table 5 – Application of truth table to the example of Figure 32	46
Table 6 – Karnaugh map related to Figure 10 when A is in up state	48
Table 7 – Karnaugh map related to Figure 10 when A is in down state	48
Table 8 – Karnaugh map related to Figure 35	53
Table A.1 – Example of equations for calculating the probability of success of basic configurations	63
Table F.1 – Impact of functional dependencies	114