

Contents

1	Introduction	10
1.1	Background and literature survey	10
1.1.1	Applications of mathematical models of cranes with a load modelled as a lumped mass	10
1.1.2	Applications of mathematical models of cranes with a load modelled as a rigid body	17
1.2	Scope and contribution of this study	19
1.3	Content and structure of the monograph	20
2	Kinematics of a boom crane	23
2.1	General description of the boom crane structure	23
2.2	Description of the motion of a link	26
3	General model of a rigid and flexible link	31
3.1	Formalism of the Lagrange equations	31
3.2	Dynamics equations of a rigid link	32
3.2.1	Generalised coordinates and homogeneous transformation matrices of a rigid link	32
3.2.2	Kinetic energy of a rigid link	33
3.2.3	Gravitational potential energy of a rigid link	36
3.2.4	Nonpotential generalised forces caused by external forces and moments acting on a rigid link	37
3.2.5	Final form of the dynamics equations	41
3.3	Dynamics equations of a flexible link	41
3.3.1	Rigid Finite Element Method - RFEM	41
3.3.2	Generalised coordinates and transformation matrices describing the motion of a flexible link	42
3.3.3	Kinetic energy of a flexible link	47
3.3.4	Gravitational potential energy of a flexible link	49
3.3.5	Nonpotential generalised forces caused by external forces and moments	50
3.3.6	Elastic potential energy and the Rayleigh dissipation function of a flexible link	50
3.3.7	Final form of the dynamics equations of a flexible link	57
4	Modelling of the crane's suspension system	58
4.1	Generalised coordinates and homogeneous transformation matrices	58
4.2	Kinetic energy of the base	59
4.3	Gravitational potential energy of the base	60

4.4	Elastic potential energy and the Rayleigh dissipation function of the wheels and outriggers	60
5	Modelling of the supporting structure of the crane	63
5.1	Generalised coordinates and homogeneous transformation matrices	64
5.2	Kinetic energy of the supporting structure	65
5.3	Gravitational potential energy of the main chain	66
6	Methods of attaching closed-loop kinematic auxiliary chains to the main structure	67
6.1	Generalised coordinates and homogeneous transformation matrices	68
6.2	Kinetic energy of the auxiliary chains	69
6.3	Gravitational potential energy of the auxiliary chains	71
6.4	Model of rigid attachment of auxiliary chains	73
6.4.1	Constraint equations	73
6.4.2	Nonpotential generalised forces	84
6.5	Model of flexible attachment of auxiliary chains	92
6.5.1	Deformation of the spring-damping element	94
6.5.2	Elastic potential energy and the Rayleigh dissipation function of the spring-damping element	98
7	Modelling of the load and its suspension on the main structure	101
7.1	Generalised coordinates and homogeneous transformation matrix	102
7.2	Kinetic energy of the load	103
7.3	Gravitational potential energy of the load	103
7.4	Elastic potential energy and the Rayleigh dissipation function of the rope(s) . . .	104
8	Modelling of drive systems	107
8.1	Rigid drive	107
8.1.1	Generalised forces and constraint equations	108
8.2	Flexible drive	111
8.2.1	Elastic potential energy and the Rayleigh dissipation function	112
9	Friction modelling	113
9.1	Selected bristles friction models	113
9.2	Recursive Newton-Euler algorithm	114
9.3	Models of the joints of a boom crane	117
9.3.1	Model of a revolute joint in coupling the crane with the car body	118
9.3.2	Model of a revolute joint in coupling the links of the crane	119
9.3.3	Model of a prismatic joint in the telescoping section	120
9.3.4	Model of a prismatic joint in a hydraulic cylinder	122
10	Final form of the dynamics equations of a mobile crane	124
11	Application of presented algorithms to the dynamics analysis of a selected boom crane	126
11.1	Description of the crane model	126
11.2	Numerical data for the parameters of the model	130
11.3	Validation of the model and evaluation of the results	134
11.4	Results of the numerical calculations	138

Summary	172
Appendixes	173
References	180
Streszczenie	191