

Contents

Preface	<i>xvii</i>
List of Symbols	<i>xxi</i>
Abbreviations	<i>xxxi</i>

Part I Fundamentals of Viscoelastic Damping 1

1 Vibration Damping 3

1.1	Overview	3
1.2	Passive, Active, and Hybrid Vibration Control	3
1.2.1	Passive Damping	3
1.2.1.1	Free and Constrained Damping Layers	3
1.2.1.2	Shunted Piezoelectric Treatments	4
1.2.1.3	Damping Layers with Shunted Piezoelectric Treatments	5
1.2.1.4	Magnetic Constrained Layer Damping (MCLD)	5
1.2.1.5	Damping with Shape Memory Fibers	6
1.2.2	Active Damping	6
1.2.3	Hybrid Damping	7
1.2.3.1	Active Constrained Layer Damping (ACLD)	7
1.2.3.2	Active Piezoelectric Damping Composites (APDC)	7
1.2.3.3	Electromagnetic Damping Composites (EMDC)	8
1.2.3.4	Active Shunted Piezoelectric Networks	8
1.3	Summary	9
	References	9

2 Viscoelastic Damping 11

2.1	Introduction	11
2.2	Classical Models of Viscoelastic Materials	11
2.2.1	Characteristics in the Time Domain	11
2.2.2	Basics for Time Domain Analysis	12
2.2.3	Detailed Time Response of Maxwell and Kelvin–Voigt Models	14
2.2.4	Detailed Time Response of the Poynting–Thomson Model	17
2.3	Creep Compliance and Relaxation Modulus	20
2.3.1	Direct Laplace Transformation Approach	22
2.3.2	Approach of Simultaneous Solution of a Linear Set of Equilibrium, Kinematic, and Constitutive Equations	23

2.4	Characteristics of the VEM in the Frequency Domain	25
2.5	Hysteresis and Energy Dissipation Characteristics of Viscoelastic Materials	27
2.5.1	Hysteresis Characteristics	27
2.5.2	Energy Dissipation	28
2.5.3	Loss Factor	28
2.5.3.1	Relationship Between Dissipation and Stored Elastic Energies	28
2.5.3.2	Relationship Between Different Strains	29
2.5.4	Storage Modulus	29
2.6	Fractional Derivative Models of Viscoelastic Materials	32
2.6.1	Basic Building Block of Fractional Derivative Models	32
2.6.2	Basic Fractional Derivative Models	33
2.6.3	Other Common Fractional Derivative Models	36
2.7	Viscoelastic Versus Other Types of Damping Mechanisms	38
2.8	Summary	40
	References	40

3 Characterization of the Properties of Viscoelastic Materials 57

3.1	Introduction	57
3.2	Typical Behavior of Viscoelastic Materials	57
3.3	Frequency Domain Measurement Techniques of the Dynamic Properties of Viscoelastic Material	59
3.3.1	Dynamic, Mechanical, and Thermal Analyzer	60
3.3.2	Oberst Test Beam Method	64
3.3.2.1	Set-Up and Beam Configurations	64
3.3.2.2	Parameter Extraction	66
3.4	Master Curves of Viscoelastic Materials	68
3.4.1	The Principle of Temperature-Frequency Superposition	68
3.4.2	The Use of the Master Curves	71
3.4.3	The Constant Temperature Lines	71
3.5	Time-Domain Measurement Techniques of the Dynamic Properties of Viscoelastic Materials	72
3.5.1	Creep and Relaxation Measurement Methods	73
3.5.1.1	Testing Equipment	73
3.5.1.2	Typical Creep and Relaxation Behavior	74
3.5.1.3	Time-Temperature Superposition	76
3.5.1.4	Boltzmann Superposition Principle	78
3.5.1.5	Relationship Between the Relaxation Modulus and Complex Modulus	80
3.5.1.6	Relationship Between the Creep Compliance and Complex Compliance	81
3.5.1.7	Relationship Between the Creep Compliance and Relaxation Modulus	83
3.5.1.8	Alternative Relationship Between the Creep Compliance and Complex Compliance	83
3.5.1.9	Alternative Relationship Between the Relaxation Modulus and Complex Modulus	84

- 3.5.1.10 Summary of the Basic Interconversion Relationship 85
 - 3.5.1.11 Practical Issues in Implementation of Interconversion Relationships 86
 - 3.5.2 Split Hopkinson Pressure Bar Method 94
 - 3.5.2.1 Overview 94
 - 3.5.2.2 Theory of 1D SHPB 95
 - 3.5.2.3 Complex Modulus of a VEM from SHPB Measurements 98
 - 3.5.3 Wave Propagation Method 105
 - 3.5.4 Ultrasonic Wave Propagation Method 109
 - 3.5.4.1 Overview 109
 - 3.5.4.2 Theory 109
 - 3.5.4.3 Measurement of the Phase Velocity and Attenuation Factor 111
 - 3.5.4.4 Typical Attenuation Factors 113
- 3.6 Summary 115
- References 116

4 Viscoelastic Materials 127

- 4.1 Introduction 127
- 4.2 Golla–Hughes–McTavish (GHM) Model 127
 - 4.2.1 Motivation of the *GHM* Model 128
 - 4.2.2 Computation of the Parameters of the *GHM* Mini-Oscillators 132
 - 4.2.3 On the Structure of the *GHM* Model 135
 - 4.2.3.1 Other Forms of *GHM* Structures 135
 - 4.2.3.2 Relaxation Modulus of the *GHM* Model 135
 - 4.2.4 Structural Finite Element Models of Rods Treated with VEM 137
 - 4.2.4.1 Unconstrained Layer Damping 138
 - 4.2.4.2 Constrained Layer Damping 142
- 4.3 Structural Finite Element Models of Beams Treated with VEM 150
 - 4.3.1 Degrees of Freedom 150
 - 4.3.2 Basic Kinematic Relationships 151
 - 4.3.3 Stiffness and Mass Matrices of the Beam/VEM Element 152
 - 4.3.4 Equations of Motion of the Beam/VEM Element 153
- 4.4 Generalized Maxwell Model (GMM) 155
 - 4.4.1 Overview 155
 - 4.4.2 Internal Variable Representation of the GMM 157
 - 4.4.2.1 Single-DOF System 157
 - 4.4.2.2 Multi-Degree of Freedom System 158
 - 4.4.2.3 Condensation of the Internal Degrees of Freedom 159
 - 4.4.2.4 Direct Solution of Coupled Structural and Internal Degrees of Freedom 160
- 4.5 Augmenting Thermodynamic Field (ATF) Model 163
 - 4.5.1 Overview 163
 - 4.5.2 Equivalent Damping Ratio of the *ATF* Model 164
 - 4.5.3 Multi-degree of Freedom *ATF* Model 165
 - 4.5.4 Integration with a Finite Element Model 165
- 4.6 Fractional Derivative (FD) Models 167
 - 4.6.1 Overview 167

4.6.2	Internal Degrees of Freedom of Fractional Derivative Models	169
4.6.3	Grunwald Approximation of Fractional Derivative	169
4.6.4	Integration Fractional Derivative Approximation with Finite Element	170
4.6.4.1	Viscoelastic Rod	170
4.6.4.2	Beam with Passive Constrained Layer Damping (PCLD) Treatment	172
4.7	Finite Element Modeling of Plates Treated with Passive Constrained Layer Damping	176
4.7.1	Overview	176
4.7.2	The Stress and Strain Characteristics	178
4.7.2.1	The Plate and the Constraining Layers	178
4.7.2.2	The VEM Layer	179
4.7.3	The Potential and Kinetic Energies	179
4.7.4	The Shape Functions	179
4.7.5	The Stiffness Matrices	181
4.7.6	The Mass Matrices	181
4.7.7	The Element and Overall Equations of Motion	182
4.8	Finite Element Modeling of Shells Treated with Passive Constrained Layer Damping	185
4.8.1	Overview	185
4.8.2	Stress–Strain Relationships	186
4.8.2.1	Shell and Constraining Layer	186
4.8.2.2	Viscoelastic Layer	187
4.8.3	Kinetic and Potential Energies	189
4.8.4	The Shape Functions	189
4.8.5	The Stiffness Matrices	189
4.8.6	The Mass Matrices	190
4.8.7	The Element and Overall Equations of Motion	191
4.9	Summary	192
	References	196

5 Finite Element Modeling of Viscoelastic Damping by Modal Strain Energy Method 205

5.1	Introduction	205
5.2	Modal Strain Energy (MSE) Method	205
5.3	Modified Modal Strain Energy (MSE) Methods	210
5.3.1	Weighted Stiffness Matrix Method (WSM)	210
5.3.2	Weighted Storage Modulus Method (WSTM)	211
5.3.3	Improved Reduction System Method (IRS)	211
5.3.4	Low Frequency Approximation Method (LFA)	213
5.4	Summary of Modal Strain Energy Methods	215
5.5	Modal Strain Energy as a Metric for Design of Damping Treatments	215
5.6	Perforated Damping Treatments	220
5.6.1	Overview	220
5.6.2	Finite Element Modeling	222
5.6.2.1	Element Energies	224

- 5.6.2.2 Topology Optimization of Unconstrained Layer Damping 227
- 5.6.2.3 Sensitivity Analysis 228
- 5.7 Summary 234
- References 234

6 Energy Dissipation in Damping Treatments 243

- 6.1 Introduction 243
- 6.2 Passive Damping Treatments of Rods 243
 - 6.2.1 Passive Constrained Layer Damping 243
 - 6.2.1.1 Equation of Motion 243
 - 6.2.1.2 Energy Dissipation 247
 - 6.2.2 Passive Unconstrained Layer Damping 248
- 6.3 Active Constrained Layer Damping Treatments of Rods 251
 - 6.3.1 Equation of Motion 251
 - 6.3.2 Boundary Control Strategy 253
 - 6.3.3 Energy Dissipation 254
- 6.4 Passive Constrained Layer Damping Treatments of Beams 257
 - 6.4.1 Basic Equations of Damped Beams 257
 - 6.4.2 Bending Energy of Beams 258
 - 6.4.3 Energy Dissipated in Beams with Passive Constrained Layer Damping 258
- 6.5 Active Constrained Layer Damping Treatments of Beams 264
- 6.6 Passive and Active Constrained Layer Damping Treatments of Plates 267
 - 6.6.1 Kinematic Relationships 268
 - 6.6.2 Energies of the PCLD and ACLD Treatments 269
 - 6.6.2.1 The Potential Energies 269
 - 6.6.2.2 The Kinetic Energy 269
 - 6.6.2.3 Work Done 269
 - 6.6.3 The Models of the PCLD and ACLD Treatments 270
 - 6.6.4 Boundary Control of Plates with ACLD Treatments 270
 - 6.6.5 Energy Dissipation and Loss Factors of Plates with PCLD and ACLD Treatments 271
- 6.7 Passive and Active Constrained Layer Damping Treatments of Axi-Symmetric Shells 274
 - 6.7.1 Background 275
 - 6.7.2 The Concept of the Active Constrained Layer Damping 276
 - 6.7.3 Variational Modeling of the Shell/ACLD System 276
 - 6.7.3.1 Main Assumptions of the Model 276
 - 6.7.3.2 Kinematic Relationships 276
 - 6.7.3.3 Stress-Strain Relationships 277
 - 6.7.3.4 Energies of Shell/ACLD System 279
 - 6.7.3.5 The Model 280
 - 6.7.4 Boundary Control Strategy 282
 - 6.7.4.1 Overview 282
 - 6.7.4.2 Control Strategy 282
 - 6.7.4.3 Implementation of the Boundary Control Strategy 283

6.7.4.4	Transverse Compliance and Longitudinal Deflection	283
6.7.5	Energy Dissipated in the ACLD Treatment of an Axi-Symmetric Shell	287
6.8	Summary	288
	References	290

Part II Advanced Damping Treatments 301

7 Vibration Damping of Structures Using Active Constrained Layer Damping 303

7.1	Introduction	303
7.2	Motivation for Using Passive and Active Constrained Layer Damping	303
7.2.1	Base Structure	304
7.2.2	Structure Treated with Unconstrained Passive Layer Damping	306
7.2.3	Structure Treated with Constrained Passive Layer Damping	308
7.2.4	Structure Treated with Active Constrained Passive Layer Damping	311
7.3	Active Constrained Layer Damping for Beams	316
7.3.1	Introduction	316
7.3.2	Concept of Active Constrained Layer Damping	316
7.3.3	Finite Element Modeling of a Beam/ACLD Assembly	318
7.3.3.1	The Model	319
7.3.3.2	Equations of Motion	322
7.3.4	Distributed-Parameter Modeling of a Beam/ACLD Assembly	328
7.3.4.1	Overview	328
7.3.4.2	The Energies and Work Done on the Beam/ACLD Assembly	328
7.3.4.3	The Distributed-Parameter Model	331
7.3.4.4	Globally Stable Boundary Control Strategy	333
7.3.4.5	Implementation of the Globally Stable Boundary Control Strategy	333
7.3.4.6	Response of the Beam/ACLD Assembly	334
7.4	Active Constrained Layer Damping for Plates	336
7.4.1	Control Forces and Moments Generated by the Active Constraining Layer	337
7.4.1.1	The In-Plane Piezoelectric Forces	337
7.4.1.2	The Piezoelectric Moments	338
7.4.1.3	Piezoelectric Sensor	338
7.4.1.4	Control Voltage to Piezoelectric Constraining Layer	339
7.4.2	Equations of Motion	339
7.5	Active Constrained Layer Damping for Shells	344
7.5.1	Control Forces and Moments Generated by the Active Constraining Layer	344
7.5.2	Equations of Motion	344
7.6	Summary	348
	References	351

8 Advanced Damping Treatments 361

- 8.1 Introduction 361
- 8.2 Stand-Off Damping Treatments 362
 - 8.2.1 Background of Stand-Off Damping Treatments 362
 - 8.2.2 The Stand-Off Damping Treatments 362
 - 8.2.3 Distributed-Parameter Model of the Stand-Off Layer Damping Treatment 364
 - 8.2.3.1 Kinematic Equations 364
 - 8.2.3.2 Constitutive Equations 365
 - 8.2.4 Distributed Transfer Function Method 369
 - 8.2.5 Finite Element Model 370
 - 8.2.6 Summary 375
- 8.3 Functionally Graded Damping Treatments 375
 - 8.3.1 Background of Functionally Graded Constrained Layer Damping 375
 - 8.3.2 Concept of Constrained Layer Damping with Functionally Graded Viscoelastic Cores 376
 - 8.3.3 Finite Element Model 377
 - 8.3.3.1 Quasi-Static Model of the Passive Constrained Damping Layer of Plunkett and Lee (1970) 377
 - 8.3.3.2 Dispersion Characteristics of Passive Constrained Damping Layer with Uniform and Functionally Graded Cores 383
 - 8.3.4 Summary 390
- 8.4 Passive and Active Damping Composite Treatments 390
 - 8.4.1 Passive Composite Damping Treatments 390
 - 8.4.2 Active Composite Damping Treatments 394
 - 8.4.3 Finite Element Modeling of Beam with APDC 396
 - 8.4.3.1 Model and Main Assumptions 396
 - 8.4.3.2 Kinematics 397
 - 8.4.3.3 Degrees of Freedom and Shape Functions 398
 - 8.4.3.4 System Energies 398
 - 8.4.3.5 Equations of Motion 400
 - 8.4.3.6 Control Law 400
 - 8.4.4 Summary 408
- 8.5 Magnetic Damping Treatments 410
 - 8.5.1 Magnetic Constrained Layer Damping Treatments 410
 - 8.5.2 Analysis of Magnetic Constrained Layer Damping Treatments 412
 - 8.5.2.1 Equation of Motion 412
 - 8.5.2.2 Response of the MCLD Treatment 414
 - 8.5.3 Passive Magnetic Composites 415
 - 8.5.3.1 Concept of Passive Magnetic Composite Treatment 417
 - 8.5.3.2 Finite Element Modeling of Beams with PMC Treatment 417
 - 8.5.4 Summary 430
- 8.6 Negative Stiffness Composites 430
 - 8.6.1 Motivation to Negative Stiffness Composites 431
 - 8.6.1.1 Sinusoidal Excitation 431

8.6.1.2	Impact Loading	436
8.6.1.3	Magnetic Composite with Negative Stiffness Inclusions	438
8.7	Summary	445
	References	445

9 Vibration Damping with Shunted Piezoelectric Networks 469

9.1	Introduction	469
9.2	Shunted Piezoelectric Patches	469
9.2.1	Basics of Piezoelectricity	469
9.2.1.1	Effect of Electrical Boundary Conditions	471
9.2.1.2	Effect of Mechanical Boundary Conditions	471
9.2.2	Basics of Shunted Piezo-Networks	472
9.2.2.1	Resistive-Shunted Circuit	474
9.2.2.2	Resistive and Inductive Shunted Circuit	475
9.2.2.3	Resistive, Capacitive, and Inductive Shunted Circuit	477
9.2.3	Electronic Synthesis of Inductances and Negative Capacitances	479
9.2.3.1	Synthesis of Inductors	479
9.2.3.2	Synthesis of Negative Capacitances	480
9.2.4	Why Negative Capacitance Is Effective?	480
9.2.5	Effectiveness of the Negative Capacitance from a Control System Perspective	482
9.2.6	Electrical Analogy of Shunted Piezoelectric Networks	485
9.3	Finite Element Modeling of Structures Treated with Shunted Piezo-Networks	487
9.3.1	Equivalent Complex Modulus Approach of Shunted Piezo-Networks	487
9.3.2	Coupled Electromechanical Field Approach of Shunted Piezo-Networks	491
9.4	Active Shunted Piezoelectric Networks	496
9.4.1	Basic Configurations	496
9.4.2	Dynamic Equations	498
9.4.2.1	Short-Circuit Configuration	498
9.4.2.2	Open-Circuit Configuration	498
9.4.2.3	Resistive-Shunted Configuration	498
9.4.3	More on the Resistive Shunting Configuration	498
9.4.4	Open-Circuit to Resistive Shunting (OC-RS) Configuration	500
9.4.4.1	Dynamic Equations	500
9.4.4.2	Switching Between OC and RS Modes	500
9.4.5	Energy Dissipation of Different Shunting Configurations	503
9.4.5.1	Energy Dissipation with Resistive Shunting	503
9.4.5.2	Energy Dissipation with OC-RS Switched Shunting	503
9.5	Multi-Mode Vibration Control with Shunted Piezoelectric Networks	504
9.5.1	Multi-Mode Shunting Approaches	504
9.5.2	Parameters of Behrens et al.'s Multi-Mode Shunting Network	507
9.5.2.1	Components of the Current Flowing Branches	507
9.5.2.2	Components of the Shunting Branches	507
9.6	Summary	510
	References	511

10 Vibration Control with Periodic Structures 523

- 10.1 Introduction 523
- 10.2 Basics of Periodic Structures 524
 - 10.2.1 Overview 524
 - 10.2.2 Transfer Matrix Method 525
 - 10.2.2.1 The Transfer Matrix 525
 - 10.2.2.2 Basic Properties of the Transfer Matrix 526
- 10.3 Filtering Characteristics of Passive Periodic Structures 533
 - 10.3.1 Overview 533
 - 10.3.2 Periodic Rods in Longitudinal Vibrations 534
- 10.4 Natural Frequencies, Mode Shapes, and Response of Periodic Structures 535
 - 10.4.1 Natural Frequencies and Response 535
 - 10.4.2 Mode Shapes 539
- 10.5 Active Periodic Structures 541
 - 10.5.1 Modeling of Active Periodic Structures 543
 - 10.5.2 Dynamics of One Cell 543
 - 10.5.2.1 Dynamics of the Passive Sub-Cell 543
 - 10.5.2.2 Dynamics of the Active Sub-Cell 543
 - 10.5.2.3 Dynamics of the Entire Cell 545
 - 10.5.2.4 Dynamics of the Entire Periodic Structure 546
- 10.6 Localization Characteristics of Passive and Active Aperiodic Structures 549
 - 10.6.1 Overview 549
 - 10.6.2 Localization Factor 550
- 10.7 Periodic Rod with Periodic Shunted Piezoelectric Patches 559
 - 10.7.1 Transfer Matrix of a Plain Rod Element 559
 - 10.7.2 Transfer Matrix of a Rod/Piezo-Patch Element 560
 - 10.7.3 Transfer Matrix of a Unit Cell 561
- 10.8 Two-Dimensional Active Periodic Structure 562
 - 10.8.1 Dynamics of Unit Cell 562
 - 10.8.2 Formulation of Phase Constant Surfaces 566
 - 10.8.3 Filtering Characteristics 568
- 10.9 Periodic Structures with Internal Resonances 569
 - 10.9.1 Dynamics of Conventional Periodic Structure 570
 - 10.9.2 Dynamics of Periodic Structure with Internal Resonances 572
 - 10.9.2.1 Equivalent Mass. Of the Mass-In-Mass Arrangement 572
 - 10.9.2.2 Transfer Matrix of the Mass-In-Mass Arrangement 572
- 10.10 Summary 578
- References 578

11 Nanoparticle Damping Composites 589

- 11.1 Introduction 589
- 11.2 Nanoparticle-Filled Polymer Composites 590
 - 11.2.1 Composites with Unidirectional Inclusions 591
 - 11.2.2 Arbitrarily Oriented Inclusion Composites 599
- 11.3 Comparisons with Classical Filler Reinforcement Methods 607

- 11.4 Applications of Carbon Black/Polymer Composites 614
 - 11.4.1 Basic Physical Characteristics 614
 - 11.4.2 Modeling of the Piezo-Resistance of CB/Polymer Composites 617
 - 11.4.3 The Piezo-Resistivity of CB/Polymer Composites 619
- 11.5 CB/Polymer Composite as a Shunting Resistance of Piezoelectric Layers 620
 - 11.5.1 Finite Element Model 620
 - 11.5.2 Condensed Model of a Unit Cell 624
- 11.6 Hybrid Composites with Shunted Piezoelectric Particles 629
 - 11.6.1 Composite Description and Assumptions 629
 - 11.6.2 Shunted Piezoelectric Inclusions 631
 - 11.6.3 Typical Performance Characteristics of Hybrid Composites 631
- 11.7 Summary 636
 - References 636

12 Power Flow in Damped Structures 651

- 12.1 Introduction 651
- 12.2 Vibrational Power 651
 - 12.2.1 Basic Definitions 651
 - 12.2.2 Relationship to System Energies 652
 - 12.2.3 Basic Characteristics of the Power Flow 653
- 12.3 Vibrational Power Flow in Beams 656
- 12.4 Vibrational Power of Plates 661
 - 12.4.1 Basic Equations of Vibrating Plates 661
 - 12.4.2 Power Flow and Structural Intensity 662
 - 12.4.3 Control of the Power Flow and Structural Intensity 668
 - 12.4.4 Power Flow and Structural Intensity for Plates with Passive and Active Constrained Layer Damping Treatments 671
- 12.5 Power Flow and Structural Intensity for Shells 679
- 12.6 Summary 682
 - References 682

Glossary 699

Appendix 703

Index 715