# Contents


Foreword xiii

Part One: Analysis of Determinate Structures 1

1 Principles of statics 3
Notation 3
1.1 Introduction 3
1.2 Representation of forces 4
1.3 Conditions of equilibrium 7
1.4 Sign convention 7
1.5 Triangle of forces 9
1.6 Free body diagram 11
1.7 Principle of superposition 13
Supplementary problems 14

2 Statically determinate pin-jointed frames 19
Notation 19
2.1 Introduction 19
2.2 Statical determinacy 20
2.3 Sign convention 22
2.4 Methods of analysis 22
(a) Method of resolution at the nodes 23
(b) Method of sections 25
(c) Method of force coefficients 27
(d) Method of substitution of members 31
Supplementary problems 35

3 Elements in flexure 41
Notation 41
3.1 Load intensity, shear force, and bending moment diagrams 41
3.2 Relationships among loading, shear force, and bending moment 45
3.3 Statical determinacy 49
(a) Beam or rigid frame with no internal hinges 50
(b) Beam or rigid frame with internal hinges or rollers 51
(c) Rigid frame with internal hinges at a node 52
3.4 Beams 53

3.5 Rigid frames 56
3.6 Three-hinged arches 63
Supplementary problems 67

**4 Elastic deformations** 71
Notation 71
4.1 Deflection of beams 72
(a) Macaulay's method 72
(b) Virtual work method 78
4.2 Deflection of rigid frames 84
(a) Virtual work method 84
(b) Conjugate beam method 87
4.3 Deflection of pin-jointed frames 93
Supplementary problems 95

**5 Influence lines** 101
Notation 101
5.1 Introduction 101
5.2 Construction of influence lines 102
5.3 Maximum effects 103
(a) Single concentrated load 103
(b) Uniformly distributed load 105
(c) Train of wheel loads 108
(d) Envelope of maximum effects 115
5.4 Pin-jointed truss 116
(a) Stringers and cross beams 116
(b) Influence lines for a Warren truss 117
(c) Influence lines for a Pratt truss 118
(d) Influence lines for a bowstring truss 119
5.5 Three-hinged arch 120
Supplementary problems 121

**6 Space frames** 125
Notation 125
6.1 Introduction 125
6.2 Conditions of equilibrium 127
6.3 Pin-jointed space frames 129
6.4 Member forces 130
Supplementary problems 134

**Answers to supplementary problems part 1** 137
Chapter 1 137
Chapter 2 138

Chapter 3 140
Chapter 4 143
Chapter 5 143
Chapter 6 144

**Part Two: Analysis of Indeterminate Structures** 145

1 **Statical indeterminacy** 147
Notation 147
1.1 Introduction 147
1.2 Indeterminacy in pin-jointed frames 148
1.3 Indeterminacy in rigid frames 150
1.4 Indeterminacy in rigid frames with internal hinges 152
(a) Hinges within a member 152
(b) Hinges at a joint 153
Supplementary problems 155
References 157

2 **Virtual work methods** 159
Notation 159
2.1 Introduction 159
2.2 Virtual work relationships 160
2.3 Sign convention 162
2.4 Illustrative examples 162
2.5 Volume integration 166
2.6 Solution of indeterminate structures 170
Supplementary problems 177
References 179

3 **Indeterminate pin-jointed frames** 181
Notation 181
3.1 Introduction 181
3.2 Frames one degree redundant 181
3.3 Frames two degrees redundant 186
3.4 Frames redundant externally 187
3.5 Frames with axial forces and bending moments 188
3.6 Two-hinged arch 192
3.7 The tied arch 195
3.8 Spandrel braced arch 197
Supplementary problems 199

4 **Conjugate beam methods** 203
Notation 203
4.1 Introduction 203
4.2 Derivation of the method 204
4.3 Sign convention 205
4.4 Support conditions 206
4.5 Illustrative examples 208
4.6 Pin-jointed frames 217
Supplementary problems 220
References 222

5 **Influence lines** 223
Notation 223
5.1 Introduction 223
5.2 General principles 224
(a) Müller–Breslau's principle 224
(b) Maxwell's reciprocal theorem 228
5.3 Moment distribution applications 232
5.4 Non-prismatic members 237
5.5 Pin-jointed frames 242
(a) Frames redundant internally 242
(b) Frames redundant externally 244
Supplementary problems 248
References 249

6 **Elastic center and column analogy methods** 251
Notation 251
6.1 Introduction 252
6.2 Elastic center method 252
6.3 Two-hinged polygonal arch 258
6.4 Influence lines for fixed-ended arches 259
6.5 Column analogy method 265
6.6 Fixed-end moments 267
6.7 Stiffness and carry-over factors 271
(a) Prismatic members 271
(b) Non-prismatic members 273
(c) Curved members 276
(d) Elastically restrained members 280
6.8 Closed rings 282
Supplementary problems 288
References 291

7 **Moment distribution methods** 293
Notation 293
7.1 Introduction 294
7.2 Sign convention and basic concepts 294
7.3 Distribution procedure for structures with joint rotations and specified translations 296
7.4 Abbreviated methods 301
(a) Hinged ends 301
(b) Cantilevers 302
(c) Symmetry in structure and applied loading 304
(d) Skew symmetry 309
7.5 Illustrative examples 310
7.6 Secondary effects 313
7.7 Non-prismatic members 315
7.8 Distribution procedure for structures subjected to unspecified joint translation 316
(a) Introduction 316
(b) The sway equations 317
(c) Sway procedure 321
(d) Illustrative examples 323
7.9 Symmetrical multi-story frames with vertical columns 332
7.10 Symmetrical multi-story frames with inclined columns 346
7.11 Frames with non-prismatic members subjected to sway 355
7.12 Frames with curved members 357
7.13 Rectangular grids 361
7.14 Direct distribution of moments and deformations 364
(a) Direct distribution of moments 365
(b) Direct distribution of deformations 367
7.15 Elastically restrained members 371
Supplementary problems 372
References 378

8 **Model analysis** 379
Notation 379
8.1 Introduction 380
8.2 Structural similitude 380
8.3 Indirect models 382
(a) Similitude requirements 382
(b) Testing technique 384
8.4 Direct models 389
Supplementary problems 395
References 398

9 **Plastic analysis and design** 399
Notation 399
9.1 Introduction 399
9.2 Formation of plastic hinges 400
9.3 Plastic moment of resistance 401
9.4 Statical method of design 406
9.5 Mechanism method of design 409
9.6 Plastic moment distribution 426
9.7 Variable repeated loads 434
9.8 Deflections at ultimate load 444
Supplementary problems 449
References 452

10 **Matrix and computer methods** 455
Notation 455
10.1 Introduction 457
10.2 Stiffness matrix method 457
(a) Introduction 457
(b) Rigid frames and grids 461
(c) Automation of procedure 483
10.3 Flexibility matrix method 498
(a) Introduction 498
(b) Automation of procedure 503
(c) Nonprismatic members 515
(d) Concordant cable profile 517
(e) Interchanging cut-back systems 522
Supplementary problems 526
References 529

11 **Elastic instability** 531
Notation 531
11.1 Introduction 532
11.2 Effect of axial loading on rigid frames without sway 533
(a) Modified moment-distribution procedure 533
(b) Determination of the critical load 537
(c) Effect of primary bending moments 544
11.3 Effect of axial loading on rigid frames subjected to sway 546
(a) Modified moment-distribution procedure 546
(b) Modified matrix methods 554
(c) Determination of the critical load 556
(d) Effect of primary bending moments 561
(e) Effect of finite displacements 565

11.4 Stability coefficient matrix method 566
Supplementary problems 573
References 575

**12 Elastic-plastic analysis** 577
Notation 577
12.1 Introduction 578
(a) Linear elastic response 579
(b) Rigid-plastic response 579
(c) Linear elastic-plastic response 580
(d) Elastic instability 580
(e) Elastic response 581
(f) Elastic-plastic response 581
12.2 The Rankine-Merchant load 582
12.3 The deteriorated critical load 586
12.4 Computer analysis 589
(a) Linear elastic-plastic analysis 590
(b) Elastic-plastic analysis 592
References 597

**Answers to supplementary problems part 2** 599
Chapter 1 599
Chapter 2 599
Chapter 3 600
Chapter 4 600
Chapter 5 601
Chapter 6 601
Chapter 7 602
Chapter 8 604
Chapter 9 604
Chapter 10 605
Chapter 11 606

**Author index** 609
**Subject index** 611